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EXERCISE 7.23 Consider the following nonlinear system: $\dot{x}_1 = x_1 + x_2$ $\dot{x}_2 = \sin(x_1 - x_2) + u$ (a) Show that the system is on strict feedback form. (b) Design a controller based on back-stepping for the system. EXERCISE 7.24 Consider the following nonlinear system: $\dot{x}_1 = -\text{sat}(x_1) + x_2$ $\dot{x}_2 = x_2 + u$

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Nonlinear control systems. Springer-Verlag, 3rd edition, 1995. James Cloutier. Nonlinear regulation and nonlinear H-infinity control via the state dependent Riccati equation technique Proceedings of First International Conference on Nonlinear Problems in Aviation and Aerospace, Florida, May, 1996. C. Mracek.

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